



Robust Control of Linear Systems Subject to Uncertain Time-Varying Parameters (Lecture Notes in Control and Information Sciences)

Francesco Amato

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The last thirty years have witnessed an enormous effort in the field of robust control of dynamical systems.

The main objective of this book is that of

presenting, in a unified framework, the main results appeared in the literature on this topic, with particular reference to the robust stability problem for linear systems subject to time-varying uncertainties. The book mainly focuses on those problems for which a definitive solution has been found; indeed most of the results we shall present are given in the form of necessary and sufficient conditions involving the feasibility of Linear Matrix Inequalities based problems. For self-containedness purposes, most of the results provided in the book are proven. We have tried to maintain the development of the proofs as simple as possible, without sacrificing the mathematical rigor. Some parts of the book (especially those contained in Chaps. 2, 3 and 5) can be taught in advanced control courses; however this work is mainly devoted to both researchers in the field of systems and control theory and engineers working in industries which want to apply the methodologies presented in the book to practical control problems. To this regard, as the various results are derived, they are immediately reinforced with real world examples.

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